

A note on an extension of a class of solutions to dynamic programming problems arising in economic growth

by

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Abstract

This note extends the finding of Benhabib and Rusticchini (1994) who provide a class of dynamic stochastic general equilibrium (DSGE) models, whose solution is characterized by a constant savings rate. We show that this class of models may be interpreted as a standard representative agent DSGE model with costly adjustment of capital.

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1 Introduction

Dynamic stochastic general equilibrium (DSGE) models have become the standard tool for analyzing many questions in business cycle research, finance, growth, and monetary economics. Except for few cases the solutions of these models must be approximated by numerical methods. In these circumstances it is often very helpful to start from a model, which is known to have an analytical solution and to approach the model of interest by way of homotopy methods (see Heer and Maußner (2009), Chapters 5 and 6). From this perspective, extensions of the class of models with analytic solutions are very valuable.

Benhabib and Rusticchini (1994), henceforth BR, extend the class of DSGE models which are known to have a solution in terms of a constant savings rate. They employ a model with two vintages of capital. In this note we firstly show that their specification is easily extended to the case of an infinite number of vintages and secondly reinterpret this specification in terms of a model with frictions in the adjustment of capital.

In the next section we present the model of BR as well as our extension and reinterpretation of it. Section three concludes and the Appendix covers a few technical details.

2 The model

BR consider a representative agent with additively time separable preferences, who discounts future utility at the rate $\delta \in (0, 1)$ and whose instantaneous utility function u is given by

$$u(c_t, 1 - L_t) = \frac{A(c_t^{1-\epsilon} - 1)}{1 - \epsilon} + w(1 - L_t), \quad (1)$$

where c denotes consumption and L hours worked. $A > 0$ and $\epsilon \geq 0$ are given parameters. w is a concave, increasing function. The agent employs labor and two vintages of capital, k_1 and k_2 , respectively, to produce output according to

$$y_t = z_t \left[(a_1 k_{1t}^{1-\epsilon} + a_2 k_{2t}^{1-\epsilon} + (1 - a_1 - a_2) L_t^{1-\epsilon}) \right]^{\frac{1}{1-\epsilon}}. \quad (2)$$

z is an iid productivity shock with support $[\underline{z}, \bar{z}]$.¹ The agent's resource constraint is

$$k_{1t+1} = y_t - c_t. \quad (3)$$

In addition, capital depreciates at the rate $\mu \in [0, 1]$ so that

$$k_{2t+1} = \mu k_{1t}. \quad (4)$$

BR prove that $c_t = \lambda y_t$ is the agent's policy function for consumption, where

$$(1 - \lambda) = \left[a_1 \delta \mathbb{E}_t (z_{t+1}^{1-\epsilon}) + a_2 \delta^2 \mu^{1-\epsilon} \mathbb{E}_t (z_{t+2}^{1-\epsilon}) \right]^{\frac{1}{\epsilon}}. \quad (5)$$

The crucial assumption that allows for this solution is that the agent's preference parameter ϵ (her coefficient of relative risk aversion) equals the reciprocal of the elasticity of substitution of the production function.

As BR note, the extension to more than two vintages is straightforward. In the case of an infinite number of vintages k_j being related to each other via

$$k_{j+1t+1} = \mu k_{jt} \quad (6)$$

the production function (2) may be written as

$$y_t = z_t \left[\sum_{j=1}^{\infty} a_j k_{jt}^{1-\epsilon} + \left(1 - \sum_{j=1}^{\infty} a_j \right) L_t^{1-\epsilon} \right]^{1/(1-\epsilon)}, \quad \sum_{j=1}^{\infty} a_j < 1. \quad (7)$$

The general solution for the savings rate $1 - \lambda$ at time $t = 0$ is then given by (see the Appendix)

$$1 - \lambda = \left[\sum_{j=1}^{\infty} a_j \delta^j \mu^{(j-1)(1-\epsilon)} E(z_{t+j}^{1-\epsilon}) \right]^{\frac{1}{\epsilon}}. \quad (8)$$

An alternative interpretation of this framework is to use a traditional CES production function with labor L_t and capital K_t as inputs,

$$y_t = z_t [\alpha L_t^{1-\epsilon} + (1 - \alpha) K_t^{1-\epsilon}]^{\frac{1}{1-\epsilon}}, \quad (9)$$

and to assume adjustment costs of capital that give rise to the transition function

$$K_t = [\beta K_{t-1}^{1-\epsilon} + (1 - \beta) k_{t-1}^{1-\epsilon}]^{\frac{1}{1-\epsilon}}, \quad (10)$$

where k_t denotes investment from foregone consumption in period t . Inserting (10) repeatedly into (9) yields

$$y_t = \left[(\alpha L_t^{1-\epsilon} + (1-\alpha)\beta \sum_{j=1}^{\infty} (1-\beta)^{j-1} k_{t-j}^{1-\epsilon}) \right]^{\frac{1}{1-\epsilon}}. \quad (11)$$

This production technique equals (7) if $a_j \mu^{(j-1)(1-\epsilon)} = (1-\alpha)\beta(1-\beta)^{j-1}$.

Thus, the savings rate at time $t = 0$ is given by

$$1 - \lambda = \left[\sum_{j=1}^{\infty} (1-\alpha)\beta(1-\beta)^{j-1} \delta^j E(z_{t+j}^{1-\epsilon}) \right]^{\frac{1}{\epsilon}}. \quad (12)$$

3 Conclusion

DSGE models featuring an analytical solution are helpful for the applied researcher because he can use this solution as a starting point for the computation of the solution of more complicated models. In this note, we have shown that the class of DSGE models provided by BR can be interpreted as a more traditional DSGE model with adjustment costs of capital. This interpretation can also be seen as a generalization of the well known closed form solution to the Ramsey problem (see e.g. McCallum (1989)) with log utility, Cobb-Douglas production and a capital accumulation equation given by $K_t = K_{t-1}^\beta k_{t-1}^{1-\beta}$ arising from (10) if ϵ equals unity.

Appendix

First, we show that there is an upper bound on output so that consumption c and (via the continuity of $u(c, 1 - L)$) expected life-time utility are finite. Let²

$$k = \bar{z} \left[\sum_{j=1}^{\infty} a_j k^{1-\epsilon} + 1 - \sum_{j=1}^{\infty} a_j \right]^{\frac{1}{1-\epsilon}}$$

denote investment if $z_t = \bar{z}$, $k_{jt} = k$ and $L_t = 1$, and $c_t = 0$. If $k_{1t+1} = k$ and $c_{t+1} = 0$, then

$$\begin{aligned} k_{1t+2} = y_{t+1} &= z_t \left[a_1 k^{1-\epsilon} + a_2 (\mu k)^{1-\epsilon} + \dots + \left(1 - \sum_{j=1}^{\infty} a_j \right) L_t^{1-\epsilon} \right]^{\frac{1}{1-\epsilon}}, \\ &\leq k = \bar{z} \left[a_1 k^{1-\epsilon} + a_2 k^{1-\epsilon} + \dots + \left(1 - \sum_{j=1}^{\infty} a_j \right) \right]^{\frac{1}{1-\epsilon}}. \end{aligned}$$

Since k_{1t+2} cannot exceed k , y_{t+2} cannot exceed $y = k$ so that $k_{1t+s} \leq k$ for all $s = 1, 2, \dots$. Thus, output, investment, and, hence, consumption are bounded.

Second, we derive the optimality conditions for an arbitrarily given number of vintages $n = 1, 2, \dots$. We focus on the condition with respect to investment k_{1t+1} , since the optimization with respect to labor input L implies a static first-order condition that can be solved for L given the sequence of vintages without knowledge of consumption c . Let $v(k_1, k_2, \dots, k_n, z)$ denote the value function, i.e. the maximum expected life-time utility of an optimal policy given the initial conditions $(k_1, k_2, \dots, k_n, z)$. This function is recursively defined by the Bellman equation:

$$v(k_1, k_2, \dots, k_n, z) = \max_{k_1^1} \frac{A((y - k_1^1)^{1-\epsilon} - 1)}{1 - \epsilon} + \delta \mathbb{E}V(k_1^1, k_2^1, \dots, k_n^1, z^1),$$

where x^i , $i = 1, 2, \dots$ denotes a variable, which is i periods ahead, and \mathbb{E} is the conditional expectations operator. The first-order condition for the maximization problem on the right-hand-side of the Bellman equation is:

$$Ac^{-\epsilon} = \delta \mathbb{E} V_1(k_1^1, \dots, k_n^1, z^1), \quad (\text{A.1})$$

where V_i denotes the derivative of V with respect to its i -argument. The envelope theorem implies that V_1 is recursively defined via:³

$$V_i(k_1, \dots, k_n, z) = Ac^{-\epsilon} y_i + \mu \delta \mathbb{E} V_{i+1}(k_1^1, \dots, k_n^1, z^1), \quad (\text{A.2a})$$

with initial condition

$$V_n(k_1, \dots, k_n, z) = Ac^{-\epsilon} y_n, \quad (\text{A.2b})$$

where y_i denotes the derivative of the production function

$$y = z \left[\sum_{j=1}^n a_j k_j^{1-\epsilon} + \left(1 - \sum_{j=1}^n a_j \right) L^{1-\epsilon} \right]^{\frac{1}{1-\epsilon}}$$

with respect to vintage $i = 1, 2, \dots, n$, which is equal to

$$y_i(\cdot) = z^{1-\epsilon} \left(\frac{k_i}{y} \right)^{-\epsilon}. \quad (\text{A.3})$$

Using (A.2) and (A.3), the first-order condition can be written as:

$$Ac^{-\epsilon} = \mathbb{E} \left\{ \sum_{i=1}^n a_i \delta^i \mu^{i-1} (c^i)^{-\epsilon} (z^i)^{1-\epsilon} \left(\frac{k_i^i}{y^i} \right)^{-\epsilon} \right\}. \quad (\text{A.4})$$

Assume $k_1^1 = (1 - \lambda)y$ so that $c = \lambda y$ and note that

$$k_i^i = \mu^{i-1} k_1^1 = \mu^{i-1} (1 - \lambda)y.$$

Then, the first-order condition (A.4) reduces to

$$1 = (1 - \lambda)^{-\epsilon} \mathbb{E} \left\{ \sum_{i=1}^n a_i \delta^i \mu^{(i-1)(1-\epsilon)} (z^i)^{1-\epsilon} \right\}. \quad (\text{A.5})$$

Obviously, the savings rate λ defined in equation (8) is the limit of (A.5) for $n \rightarrow \infty$ (and z^i replaced with z_{t+j} .)

Notes

¹BR, p. 809, assume that z follows a first-order autoregressive process. However, as they note on p. 811, the savings rate λ will only be constant, if z is iid.

²Note that this definition implies the parameter restriction $\bar{z}^{1-\epsilon} \sum_{j=1}^{\infty} a_j < 1$, since

$$k = \left[\frac{1 - \sum_{j=1}^{\infty} a_j}{1 - \bar{z}^{1-\epsilon} \sum_{j=1}^{\infty} a_j} \right]^{\frac{1}{1-\epsilon}}.$$

Since z implicitly defines the scale for output, this condition is not restrictive.

³More explicitly, let $k_1^1 = h(k_1, \dots, k_n, z)$ denote the solution of the first-order condition (A.1). Then, the Bellman equation can be written as

$$v(k_1, \dots, k_n, z) = \frac{A((y - h(k_1, \dots, k_n, z))^{1-\epsilon})}{1 - \epsilon} + \delta \mathbb{E}V(k_1^1, \mu k_1, k_3^1, \dots, k_n^1, z^1).$$

Differentiating with respect to k_1 yields:

$$\begin{aligned} V_1(k_1, \dots, k_n, z) &= Ac^{-\epsilon} y_1 + \mu \delta \mathbb{E}V_2(k_1^1, \dots, k_n^1, z^1) + h_1(\cdot) \{(\delta V_1(k_1^1, \dots, k_n^1, z^1)) - Ac^{-\epsilon}\}, \\ &= Ac^{-\epsilon} y_1 + \mu \delta \mathbb{E}V_2(k_1^1, \dots, k_n^1, z^1) \end{aligned}$$

since the term in braces vanishes due to the first-order condition (A.1). In the same way one can derive $V_2(k_1, \dots, k_n, z) = Ac^{-\epsilon} y_2 + \mu \delta \mathbb{E}V_3(k_1^1, \dots, k_n^1, z^1)$ etc.

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